

# Variational Mean Field Games: on estimates on the density and the pressure and their consequences for the Lagrangian point of view

---

Hugo Lavenant<sup>a</sup>

December 13th, 2019

SIAM conference on PDE. La Quinta, California, USA

---

<sup>a</sup>Department of Mathematics, University of British Columbia

# Variational Mean Field Games of first order <sup>1</sup>

$$\min_{\rho, v} \left[ \right]$$

where  $\rho : [0, T] \rightarrow \mathcal{P}(\Omega)$  and  $v : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  while

$$\partial_t \rho + \nabla \cdot (\rho v) = 0.$$

The initial density  $\rho_0$  is given,  $V, \Psi : \Omega \rightarrow \mathbb{R}$  are potentials.

---

<sup>1</sup>Benamou, Carlier and Santambrogio, *Variational Mean Field Games* (2016).

# Variational Mean Field Games of first order <sup>1</sup>

$$\min_{\rho, v} \left[ \underbrace{\frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt}_{\text{Optimal evolution}} + \underbrace{\int_{\Omega} \Psi \rho_T \, dx}_{\text{Terminal cost}} \right]$$

where  $\rho : [0, T] \rightarrow \mathcal{P}(\Omega)$  and  $v : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  while

$$\partial_t \rho + \nabla \cdot (\rho v) = 0.$$

The initial density  $\rho_0$  is given,  $V, \Psi : \Omega \rightarrow \mathbb{R}$  are potentials.

---

<sup>1</sup>Benamou, Carlier and Santambrogio, *Variational Mean Field Games* (2016).

# Variational Mean Field Games of first order <sup>1</sup>

$$\min_{\rho, v} \left[ \underbrace{\frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt}_{\text{Optimal evolution}} + \underbrace{\int_0^T \int_{\Omega} V \rho_t \, dx dt}_{\text{Favors congestion}} + \underbrace{\int_{\Omega} \Psi \rho_T \, dx}_{\text{Terminal cost}} \right]$$

where  $\rho : [0, T] \rightarrow \mathcal{P}(\Omega)$  and  $v : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  while

$$\partial_t \rho + \nabla \cdot (\rho v) = 0.$$

The initial density  $\rho_0$  is given,  $V, \Psi : \Omega \rightarrow \mathbb{R}$  are potentials.

---

<sup>1</sup>Benamou, Carlier and Santambrogio, *Variational Mean Field Games* (2016).

# Variational Mean Field Games of first order <sup>1</sup>

$$\min_{\rho, v} \left[ \underbrace{\frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt}_{\text{Optimal evolution}} + \underbrace{\int_0^T \int_{\Omega} V \rho_t \, dx dt}_{\text{Favors congestion}} + \underbrace{\int_0^T F(\rho_t) \, dt}_{\text{Penalizes congestion}} + \underbrace{\int_{\Omega} \Psi \rho_T \, dx}_{\text{Terminal cost}} \right]$$

where  $\rho : [0, T] \rightarrow \mathcal{P}(\Omega)$  and  $v : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  while

$$\partial_t \rho + \nabla \cdot (\rho v) = 0.$$

The initial density  $\rho_0$  is given,  $V, \Psi : \Omega \rightarrow \mathbb{R}$  are potentials.

---

<sup>1</sup>Benamou, Carlier and Santambrogio, *Variational Mean Field Games* (2016).

# Variational Mean Field Games of first order <sup>1</sup>

$$\min_{\rho, v} \left[ \underbrace{\frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt}_{\text{Optimal evolution}} + \underbrace{\int_0^T \int_{\Omega} V \rho_t \, dx dt}_{\text{Favors congestion}} + \underbrace{\int_0^T F(\rho_t) \, dt}_{\text{Penalizes congestion}} + \underbrace{\int_{\Omega} \Psi \rho_T \, dx}_{\text{Terminal cost}} \right]$$

where  $\rho : [0, T] \rightarrow \mathcal{P}(\Omega)$  and  $v : [0, T] \times \Omega \rightarrow \mathbb{R}^d$  while

$$\partial_t \rho + \nabla \cdot (\rho v) = 0.$$

The initial density  $\rho_0$  is given,  $V, \Psi : \Omega \rightarrow \mathbb{R}$  are potentials.

The function  $F : \mathcal{P}(\Omega) \rightarrow \mathbb{R}$  is convex. Two cases:

$$F(\rho) = \begin{cases} \int_{\Omega} f(\rho) \, dx & \text{"soft congestion",} \\ 0 \text{ if } \rho \leq 1, +\infty \text{ otherwise} & \text{"hard congestion".} \end{cases}$$

<sup>1</sup>Benamou, Carlier and Santambrogio, *Variational Mean Field Games* (2016).

## Mean Field Games: Lagrangian interpretation

If  $\rho$  is a minimizer of the problem, there exists  $Q \in \mathcal{P}(C([0, T], \Omega))$  such that  $Q(d\gamma)$  represents the proportion of agents following the strategy  $\gamma$ .

## Mean Field Games: Lagrangian interpretation

If  $\rho$  is a minimizer of the problem, there exists  $Q \in \mathcal{P}(C([0, T], \Omega))$  such that  $Q(d\gamma)$  represents the proportion of agents following the strategy  $\gamma$ .

Denote  $e_t : C([0, T], \Omega) \rightarrow \Omega$  the evaluation at time  $t$ :

- for all  $t$ ,  $e_t\#Q = \rho_t$ ,



## Mean Field Games: Lagrangian interpretation

If  $\rho$  is a minimizer of the problem, there exists  $Q \in \mathcal{P}(C([0, T], \Omega))$  such that  $Q(\gamma)d\gamma$  represents the proportion of agents following the strategy  $\gamma$ .

Denote  $e_t : C([0, T], \Omega) \rightarrow \Omega$  the evaluation at time  $t$ :

- for all  $t$ ,  $e_t \# Q = \rho_t$ ,
- $Q$ -a.e. curve  $\gamma$  solves the control problem

$$\min_{\omega \text{ s.t. } \omega(0)=\gamma(0)} \left[ \int_0^T \left( \frac{1}{2} |\dot{\omega}_t|^2 + V(\omega_t) + p_t(\omega_t) \right) dt + \Psi(\omega_T) \right].$$

# Mean Field Games: Lagrangian interpretation

If  $\rho$  is a minimizer of the problem, there exists  $Q \in \mathcal{P}(C([0, T], \Omega))$  such that  $Q(d\gamma)$  represents the proportion of agents following the strategy  $\gamma$ .

Denote  $e_t : C([0, T], \Omega) \rightarrow \Omega$  the evaluation at time  $t$ :

- for all  $t$ ,  $e_t \# Q = \rho_t$ ,
- $Q$ -a.e. curve  $\gamma$  solves the control problem

$$\min_{\omega \text{ s.t. } \omega(0)=\gamma(0)} \left[ \int_0^T \left( \frac{1}{2} |\dot{\omega}_t|^2 + V(\omega_t) + p_t(\omega_t) \right) dt + \Psi(\omega_T) \right].$$

The field  $p : [0, T] \times \Omega \rightarrow \mathbb{R}$  is the price or the pressure.

$$p_t(x) \quad \begin{cases} = f'(\rho_t(x)) & \text{(Soft congestion)} \\ \geq 0 \text{ and } = 0 \text{ if } \rho_t(x) < 1 & \text{(Hard congestion)} \end{cases}$$

# Mean Field Games

Mean Field Games of first order with local couplings:

- Each agent tries to minimize  $\Psi$  at the final time but try to avoid the others.

# Mean Field Games

Mean Field Games of first order with local couplings:

- Each agent tries to minimize  $\Psi$  at the final time but try to avoid the others.
- The effect of the other agents is only felt by their mean field effect through the price  $p$ .

# Mean Field Games

Mean Field Games of first order with local couplings:

- Each agent tries to minimize  $\Psi$  at the final time but try to avoid the others.
- The effect of the other agents is only felt by their mean field effect through the price  $p$ .
- Quadratic (because on the square on the velocity), first order (no noise) and potential (comes from the minimization of a functional).

# Mean Field Games: Eulerian interpretation

Value function for a single agent:

$$\varphi(t, x) := \min_{\omega \text{ s.t. } \omega(t)=x} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_t|^2 + V(\omega_t) + p_t(\omega_t) \right) dt + \Psi(\omega_T) \right].$$

# Mean Field Games: Eulerian interpretation

Value function for a single agent:

$$\varphi(t, x) := \min_{\omega \text{ s.t. } \omega(t)=x} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_t|^2 + V(\omega_t) + \rho_t(\omega_t) \right) dt + \Psi(\omega_T) \right].$$

It solves a Hamilton-Jacobi equation. The optimal control is

$$\dot{\gamma}(t) = -\nabla \varphi(t, \gamma(t)) = v(t, \gamma(t)).$$

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho v) & = 0, \\ \rho_0 & \text{given,} \\ -\partial_t \varphi + \frac{1}{2} |\nabla \varphi|^2 & = V + \rho, \\ \varphi(T, \cdot) & = \Psi, \\ v & = -\nabla \varphi. \end{cases}$$

# Regularity issues

Abstract idea of Mean Field Games



# Regularity issues

Abstract idea of Mean Field Games

Variational problem  
Easy existence of  $\rho, v, p, \varphi$

# Regularity issues

Abstract idea of Mean Field Games

Variational problem  
Easy existence of  $\rho, v, p, \varphi$

Lagrangian interpretation  
 $Q$  describing the distribution of strategies

Eulerian interpretation  
System of PDE for  $\rho, v, p, \varphi$

# Regularity issues

Abstract idea of Mean Field Games

Variational problem  
Easy existence of  $\rho, v, p, \varphi$

Optimality conditions

Lagrangian interpretation  
 $Q$  describing the distribution of strategies

Control theory

Eulerian interpretation  
System of PDE for  $\rho, v, p, \varphi$

# Regularity issues

Abstract idea of Mean Field Games

Variational problem  
Easy existence of  $\rho, v, p, \varphi$

Optimality conditions

Lagrangian interpretation  
 $Q$  describing the distribution of strategies

Control theory

Eulerian interpretation  
System of PDE for  $\rho, v, p, \varphi$

## Questions

What regularity can be deduced on  $\rho$  on  $p$  from the variational formulation?

Does it justify the Lagrangian and Eulerian systems?

## Regularity of $\rho$ : soft congestion <sup>2</sup>

$$\min_{\rho, v} \left[ \frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt + \int_0^T \int_{\Omega} V \rho_t \, dx dt + \int_0^T \int_{\Omega} f(\rho_t) \, dx dt + \int_{\Omega} \Psi \rho_T \, dx. \right]$$

with  $\partial_t \rho + \nabla \cdot (\rho v) = 0$ .

---

<sup>2</sup>L. and Santambrogio, *Optimal density evolution with congestion:  $L^\infty$  bounds via flow interchange techniques and applications to variational Mean Field Games* (2018).

## Regularity of $\rho$ : soft congestion <sup>2</sup>

$$\min_{\rho, V} \left[ \frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt + \int_0^T \int_{\Omega} V \rho_t \, dx dt + \int_0^T \int_{\Omega} f(\rho_t) \, dx dt + \int_{\Omega} \Psi \rho_T \, dx. \right]$$

with  $\partial_t \rho + \nabla \cdot (\rho v) = 0$ .

### Theorem

Assume  $V$  is Lipschitz,  $\Psi \in C^{1,1}$  and  $f'(s) \geq s^\alpha$  with  $\alpha \geq -1$ . Then, for every  $t < T$ , the measure  $\rho$  belongs to  $L^\infty([t, T] \times \Omega)$ .

---

<sup>2</sup>L. and Santambrogio, *Optimal density evolution with congestion:  $L^\infty$  bounds via flow interchange techniques and applications to variational Mean Field Games* (2018).

## Regularity of $\rho$ : soft congestion <sup>2</sup>

$$\min_{\rho, V} \left[ \frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt + \int_0^T \int_{\Omega} V \rho_t \, dx dt + \int_0^T \int_{\Omega} f(\rho_t) \, dx dt + \int_{\Omega} \Psi \rho_T \, dx. \right]$$

with  $\partial_t \rho + \nabla \cdot (\rho v) = 0$ .

### Theorem

Assume  $V$  is Lipschitz,  $\Psi \in C^{1,1}$  and  $f''(s) \geq s^\alpha$  with  $\alpha \geq -1$ . Then, for every  $t < T$ , the measure  $\rho$  belongs to  $L^\infty([t, T] \times \Omega)$ .

### Corollary

Under the assumption of the previous theorem, if  $f'$  is bounded from below then  $\rho = f'(\rho)$  belongs to  $L^\infty([t, T] \times \Omega)$ .

---

<sup>2</sup>L. and Santambrogio, *Optimal density evolution with congestion:  $L^\infty$  bounds via flow interchange techniques and applications to variational Mean Field Games* (2018).

## Idea of the proof

If  $m > 1$ ,

$$\int_{\Omega} \rho^m$$



## Idea of the proof

If  $m > 1$ ,

$$\frac{d^2}{dt^2} \int_{\Omega} \rho^m$$

## Idea of the proof

If  $m > 1$ ,

$$\frac{d^2}{dt^2} \int_{\Omega} \rho^m \geq m(m-1) \int_{\Omega} |\nabla \rho|^2 \rho^{m-2} f''(\rho) + [\text{Low order}]$$

## Idea of the proof

If  $m > 1$ ,

$$\begin{aligned} \frac{d^2}{dt^2} \int_{\Omega} \rho^m &\geq m(m-1) \int_{\Omega} |\nabla \rho|^2 \rho^{m-2} f''(\rho) + [\text{Low order}] \\ &\sim C(m) \int_{\Omega} \left| \nabla \left( \rho^{(m+1+\alpha)/2} \right) \right|^2 \end{aligned}$$

## Idea of the proof

If  $m > 1$ , with  $\beta > 1$  such that  $H^1(\Omega) \hookrightarrow L^{2\beta}(\Omega)$ ,

$$\begin{aligned} \frac{d^2}{dt^2} \int_{\Omega} \rho^m &\geq m(m-1) \int_{\Omega} |\nabla \rho|^2 \rho^{m-2} f''(\rho) + [\text{Low order}] \\ &\sim C(m) \int_{\Omega} \left| \nabla \left( \rho^{(m+1+\alpha)/2} \right) \right|^2 \\ &\geq C(m) \left( \int_{\Omega} \rho^{\beta(m+1+\alpha)} \right)^{1/\beta}. \end{aligned}$$

## Idea of the proof

If  $m > 1$ , with  $\beta > 1$  such that  $H^1(\Omega) \hookrightarrow L^{2\beta}(\Omega)$ ,

$$\begin{aligned} \frac{d^2}{dt^2} \int_{\Omega} \rho^m &\geq m(m-1) \int_{\Omega} |\nabla \rho|^2 \rho^{m-2} f''(\rho) + [\text{Low order}] \\ &\sim C(m) \int_{\Omega} \left| \nabla \left( \rho^{(m+1+\alpha)/2} \right) \right|^2 \\ &\geq C(m) \left( \int_{\Omega} \rho^{\beta(m+1+\alpha)} \right)^{1/\beta}. \end{aligned}$$

Integration with respect to time and *Moser iterations*.



## Regularity of $\rho$ : hard congestion<sup>3</sup>

$$\min_{\rho, v} \left[ \frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt + \int_0^T \int_{\Omega} V \rho_t \, dx dt + \int_{\Omega} \Psi \rho_T \, dx. \right]$$

with  $\partial_t \rho + \nabla \cdot (\rho v) = 0$  and the constraint  $\rho \leq 1$ .

---

<sup>3</sup>L. and Santambrogio, *New estimates on the regularity of the pressure in density-constrained Mean Field Games* (2019).

## Regularity of $\rho$ : hard congestion<sup>3</sup>

$$\min_{\rho, v} \left[ \frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt + \int_0^T \int_{\Omega} V \rho_t \, dx dt + \int_{\Omega} \Psi \rho_T \, dx. \right]$$

with  $\partial_t \rho + \nabla \cdot (\rho v) = 0$  and the constraint  $\rho \leq 1$ .

$d$  is the dimension of the ambient space.

### Theorem

Assume  $\nabla V \in L^q$  with  $q > d$ . Then  $p$  belongs to  $L^\infty([0, T] \times \Omega)$  with a norm depending only on  $\|\nabla V\|_{L^q}$  and  $\Omega$ .

---

<sup>3</sup>L. and Santambrogio, *New estimates on the regularity of the pressure in density-constrained Mean Field Games* (2019).

## Regularity of $\rho$ : hard congestion<sup>3</sup>

$$\min_{\rho, V} \left[ \frac{1}{2} \int_0^T \int_{\Omega} \frac{1}{2} |v_t|^2 \rho_t \, dx dt + \int_0^T \int_{\Omega} V \rho_t \, dx dt + \int_{\Omega} \Psi \rho_T \, dx. \right]$$

with  $\partial_t \rho + \nabla \cdot (\rho v) = 0$  and the constraint  $\rho \leq 1$ .

$d$  is the dimension of the ambient space.

### Theorem

Assume  $\nabla V \in L^q$  with  $q > d$ . Then  $p$  belongs to  $L^\infty([0, T] \times \Omega)$  with a norm depending only on  $\|\nabla V\|_{L^q}$  and  $\Omega$ .

The proof relies on an inequality

$$\Delta(\rho + V) \geq -D_{tt} \ln \rho \underbrace{\geq}_{\text{on } \{\rho > 0\}} 0.$$

<sup>3</sup>L. and Santambrogio, *New estimates on the regularity of the pressure in density-constrained Mean Field Games* (2019).



## Consequences: regularity of the value function<sup>4 5</sup>

Previous results on the regularity of  $\varphi$  solving:

$$-\partial_t \varphi + \frac{1}{2} |\nabla \varphi|^2 = g, \quad g \in L^\infty$$

---

<sup>4</sup>Cardaliaguet and Silvestre, *Hölder continuity to Hamilton-Jacobi equations with superquadratic growth in the gradient and unbounded right-hand side* (2012).

<sup>5</sup>Cardaliaguet, Porretta, and Tonon, *Sobolev regularity for the first order Hamilton-Jacobi equation* (2015).

## Consequences: regularity of the value function <sup>4 5</sup>

Previous results on the regularity of  $\varphi$  solving:

$$-\partial_t \varphi + \frac{1}{2} |\nabla \varphi|^2 = g, \quad g \in L^\infty$$

- $\varphi$  is Hölder-continuous on  $(0, T) \times \Omega$ ,
- $\partial_t \varphi \in L^{1+\varepsilon}$  and  $\nabla \varphi \in L^{2+\varepsilon}$ ,
- The Hamilton-Jacobi equation is satisfied in the almost everywhere sense.

---

<sup>4</sup>Cardaliaguet and Silvestre, *Hölder continuity to Hamilton-Jacobi equations with superquadratic growth in the gradient and unbounded right-hand side* (2012).

<sup>5</sup>Cardaliaguet, Porretta, and Tonon, *Sobolev regularity for the first order Hamilton-Jacobi equation* (2015).

## Consequence: Lagrangian point of view <sup>6 7</sup>

Case of soft congestion with a pressure in  $L^\infty((0, T] \times \Omega)$ .

---

<sup>6</sup>Ambrosio and Figalli, *Geodesics in the space of measure-preserving maps and plans* (2009).

<sup>7</sup>Cardaliaguet, Mészáros, and Santambrogio, *First order mean field games with density constraints: pressure equals price* (2016).

## Consequence: Lagrangian point of view <sup>6 7</sup>

Case of soft congestion with a pressure in  $L^\infty((0, T] \times \Omega)$ . Pointwise representative of the pressure:

$$\hat{p}_t(x) = \limsup_{\varepsilon \rightarrow 0} \int_{B(x, \varepsilon)} p_t(y) dy.$$

---

<sup>6</sup>Ambrosio and Figalli, *Geodesics in the space of measure-preserving maps and plans* (2009).

<sup>7</sup>Cardaliaguet, Mészáros, and Santambrogio, *First order mean field games with density constraints: pressure equals price* (2016).

## Consequence: Lagrangian point of view <sup>6 7</sup>

Case of soft congestion with a pressure in  $L^\infty((0, T] \times \Omega)$ . Pointwise representative of the pressure:

$$\hat{p}_t(x) = \limsup_{\varepsilon \rightarrow 0} \int_{B(x, \varepsilon)} p_t(y) dy.$$

There exists  $Q \in \mathcal{P}(C([0, T], \Omega))$  such that

- for all  $t$ ,  $e_t \# Q = \rho_t$ ,
- for  $Q$ -a.e. curve  $\gamma$ , for all  $t > 0$ ,  $\gamma$  is a minimizer of

$$\min_{\omega \text{ s.t. } \omega(t) = \gamma(t)} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right].$$

---

<sup>6</sup>Ambrosio and Figalli, *Geodesics in the space of measure-preserving maps and plans* (2009).

<sup>7</sup>Cardaliaguet, Mészáros, and Santambrogio, *First order mean field games with density constraints: pressure equals price* (2016).

## Link between Eulerian and Lagrangian point of view

The Eulerian value function  $\varphi$  is in fact a Lagrangian value function. For  $t > 0$ , for  $\rho_t$  a.e.  $x$ ,

$$\varphi(t, x) = \min_{\omega \text{ s.t. } \omega(t)=x} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right]$$

## Link between Eulerian and Lagrangian point of view

The Eulerian value function  $\varphi$  is in fact a Lagrangian value function. For  $t > 0$ , for  $\rho_t$  a.e.  $x$ ,

$$\varphi(t, x) = \min_{\omega \text{ s.t. } \omega(t)=x} \underbrace{\left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right]}_{:= \tilde{\varphi}(t, x)}.$$

## Link between Eulerian and Lagrangian point of view

The Eulerian value function  $\varphi$  is in fact a Lagrangian value function. For  $t > 0$ , for  $\rho_t$  a.e.  $x$ ,

$$\varphi(t, x) = \min_{\omega \text{ s.t. } \omega(t)=x} \underbrace{\left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right]}_{:= \tilde{\varphi}(t, x)}.$$

- The inequality  $\varphi \leq \tilde{\varphi}$  part follows by a smoothing argument of the pressure.



## Link between Eulerian and Lagrangian point of view

The Eulerian value function  $\varphi$  is in fact a Lagrangian value function. For  $t > 0$ , for  $\rho_t$  a.e.  $x$ ,

$$\varphi(t, x) = \underbrace{\min_{\omega \text{ s.t. } \omega(t)=x} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right]}_{:= \tilde{\varphi}(t, x)}.$$

- The inequality  $\varphi \leq \tilde{\varphi}$  part follows by a smoothing argument of the pressure.
- On the other hand for  $Q$ -a.e.  $\gamma$ ,

$$\tilde{\varphi}(t, \gamma(t)) = \int_t^T \left( \frac{1}{2} |\dot{\gamma}_s|^2 + V(\gamma) + \hat{p}_s(\gamma) \right) ds + \Psi(\gamma_T).$$

## Link between Eulerian and Lagrangian point of view

The Eulerian value function  $\varphi$  is in fact a Lagrangian value function. For  $t > 0$ , for  $\rho_t$  a.e.  $x$ ,

$$\varphi(t, x) = \underbrace{\min_{\omega \text{ s.t. } \omega(t)=x} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right]}_{:= \tilde{\varphi}(t, x)}.$$

- The inequality  $\varphi \leq \tilde{\varphi}$  part follows by a smoothing argument of the pressure.
- On the other hand for  $Q$ -a.e.  $\gamma$ ,

$$\tilde{\varphi}(t, \gamma(t)) = \int_t^T \left( \frac{1}{2} |\dot{\gamma}_s|^2 + V(\gamma) + \hat{p}_s(\gamma) \right) ds + \Psi(\gamma_T).$$

- Integrating w.r.t.  $Q$  gives

$$\int_{\Omega} \tilde{\varphi} \rho_t \leq \frac{1}{2} \int_t^T \int_{\Omega} \frac{1}{2} |v|^2 \rho + \int_0^T \int_{\Omega} V \rho + \int_0^T \int_{\Omega} \rho \hat{p} + \int_{\Omega} \Psi \rho_T$$

## Link between Eulerian and Lagrangian point of view

The Eulerian value function  $\varphi$  is in fact a Lagrangian value function. For  $t > 0$ , for  $\rho_t$  a.e.  $x$ ,

$$\varphi(t, x) = \underbrace{\min_{\omega \text{ s.t. } \omega(t)=x} \left[ \int_t^T \left( \frac{1}{2} |\dot{\omega}_s|^2 + V(\omega_s) + \hat{p}_s(\omega_s) \right) ds + \Psi(\omega_T) \right]}_{:= \tilde{\varphi}(t, x)}.$$

- The inequality  $\varphi \leq \tilde{\varphi}$  part follows by a smoothing argument of the pressure.
- On the other hand for  $Q$ -a.e.  $\gamma$ ,

$$\tilde{\varphi}(t, \gamma(t)) = \int_t^T \left( \frac{1}{2} |\dot{\gamma}_s|^2 + V(\gamma) + \hat{p}_s(\gamma) \right) ds + \Psi(\gamma_T).$$

- Integrating w.r.t.  $Q$  gives

$$\int_{\Omega} \tilde{\varphi} \rho_t \leq \frac{1}{2} \int_t^T \int_{\Omega} |\dot{V}|^2 \rho + \int_0^T \int_{\Omega} V \rho + \int_0^T \int_{\Omega} \rho \hat{p} + \int_{\Omega} \Psi \rho_T \stackrel{\text{by optimality}}{=} \int_{\Omega} \varphi \rho_t.$$

Thank you for your attention