

Gradient flows of potential energies in the geometry of Sinkhorn divergences



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Bocconi University

Workshop “Wasserstein Gradient flows in Math and Machine Learning”

Banff (Canada), July 4, 2025

Joint work with



Mathis Hardion



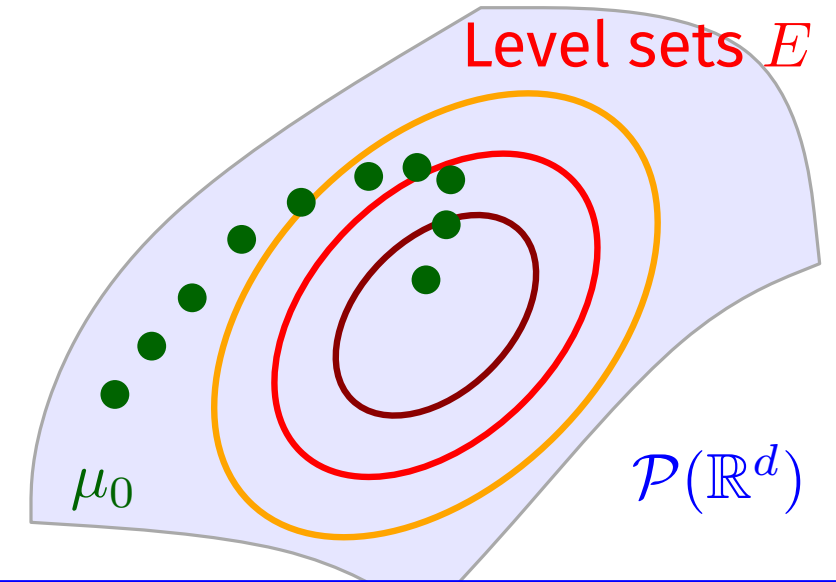
Mathis' master thesis available online, preprint of the article on arxiv hopefully soon.

The JKO scheme

$E : \mathcal{P}(\mathbb{R}^d) \rightarrow [0, +\infty]$ and $\mu_0 \in \mathcal{P}(\mathbb{R}^d)$.

$$\text{OT}(\mu, \nu) = \min_{\pi \in \Pi(\mu, \nu)} \iint_{\mathbb{R}^d \times \mathbb{R}^d} |x - y|^2 \, d\pi(x, y).$$

Subset of $\mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d)$, coupling between μ and ν



Minimizing movement scheme / JKO scheme. For $\tau > 0$ iterate for $k \geq 0$,

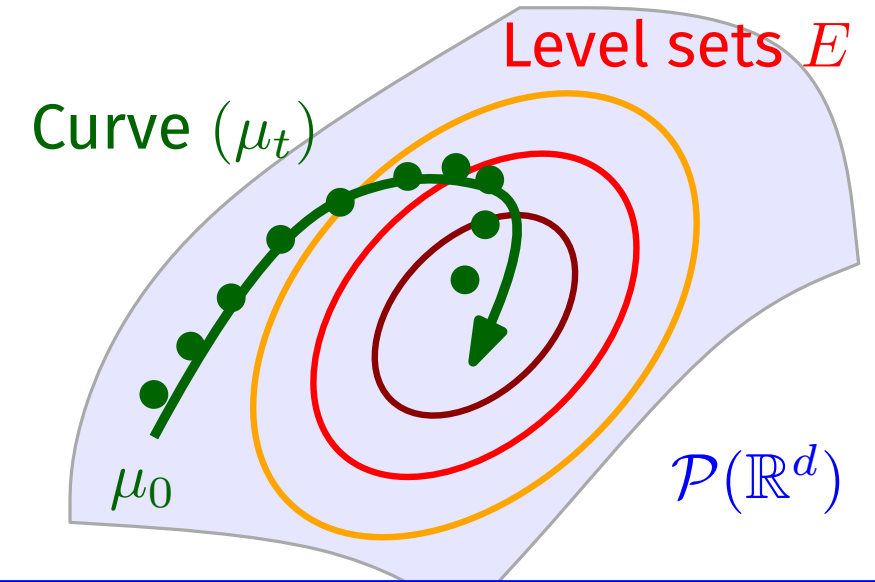
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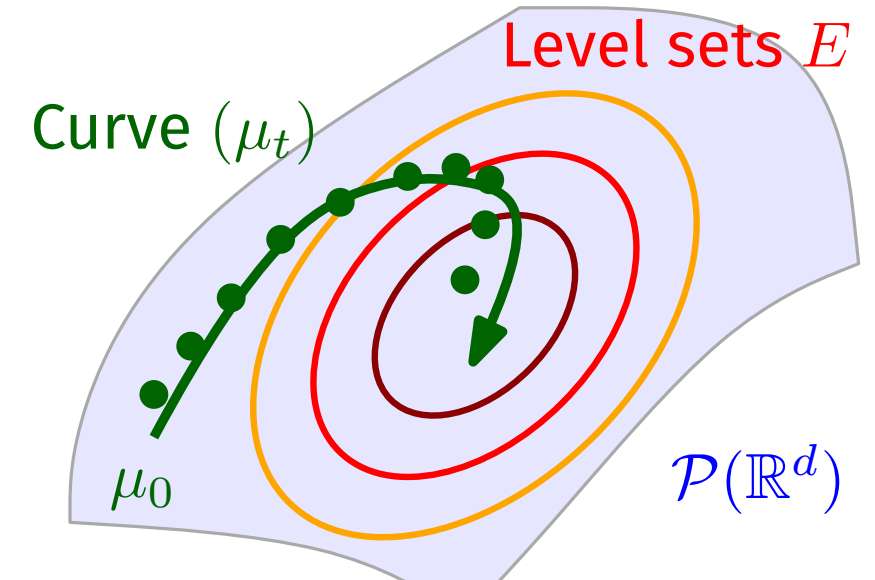
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Question: how to use entropic OT instead of OT?

With entropic optimal transport?

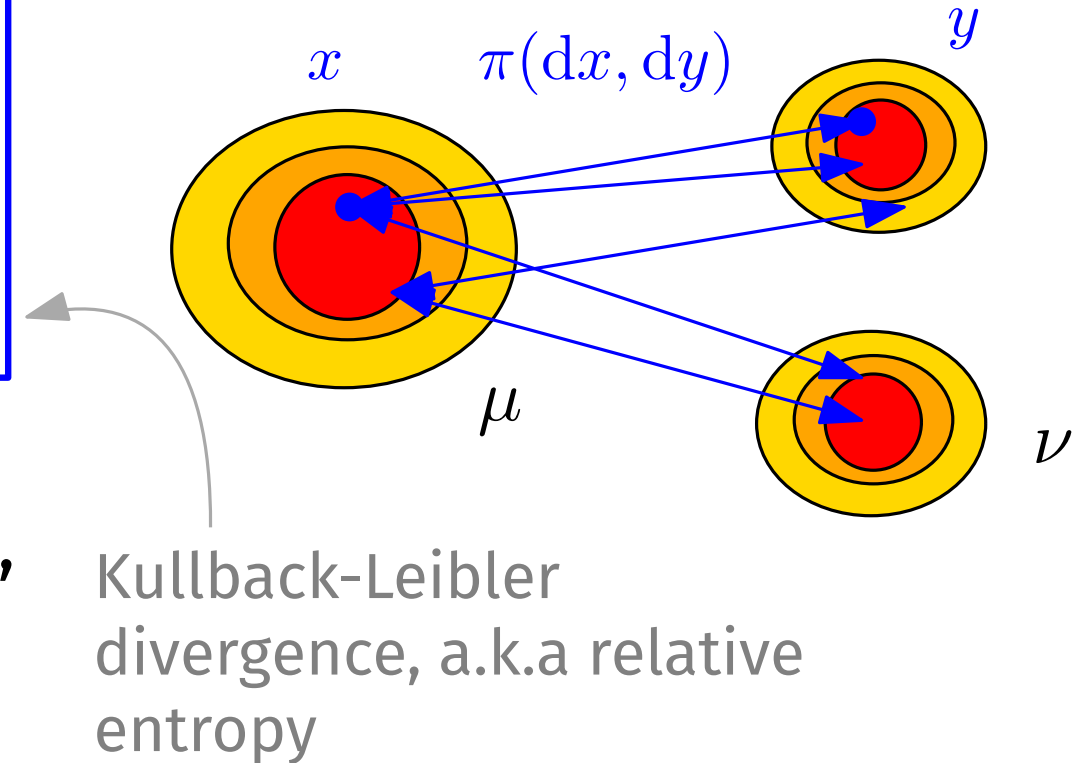
(X, d) compact metric space with symmetric cost function c , and $\varepsilon > 0$.

Definition

$$\text{OT}_\varepsilon(\mu, \nu) = \min_{\pi \in \Pi(\mu, \nu)} \iint_{X \times X} c(x, y) \, d\pi(x, y) + \varepsilon \text{KL}(\pi | \mu \otimes \nu)$$

Why?

1. easier to compute (**Sinkhorn algorithm**),
2. better statistical complexity,
3. smoother dependence in (μ, ν) .



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$\rightsquigarrow$ Global minima of E not stable.

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$\rightsquigarrow$ scaling $\varepsilon \ll \tau$ or $\varepsilon \sim \tau$.

[Carlier, Duval, Peyré, Schmitzer, 2017]

[Baradat, Hraivoronska, Santambrogio, 2025]

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Today: I will keep ε fixed.

Using Sinkhorn divergences

As $\text{OT}_\varepsilon(\mu, \mu) > 0$, **debias** by defining **Sinkhorn divergence**

$$S_\varepsilon(\mu, \nu) = \text{OT}_\varepsilon(\mu, \nu) - \frac{1}{2}\text{OT}_\varepsilon(\mu, \mu) - \frac{1}{2}\text{OT}_\varepsilon(\nu, \nu).$$

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Assumption
until the end
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Theorem Assume $\exp(-c/\varepsilon)$ positive definite universal kernel.

1. $S_\varepsilon(\mu, \nu) \geq 0$ with equality iff $\mu = \nu$, and S_ε “metrizes” weak convergence.
2. S_ε convex in each of its inputs.

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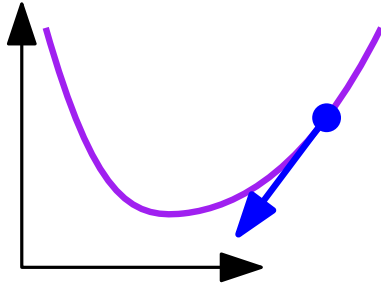
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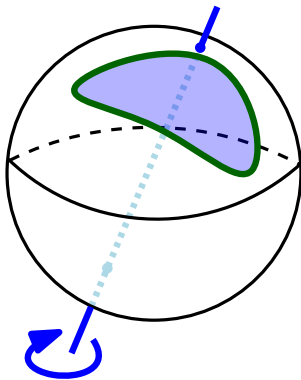
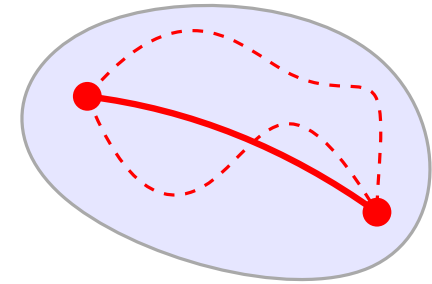
Today: Study of SJKO with
 $E(\mu) = \int V \, d\mu$ potential energy.

(if $\varepsilon = 0$ convergence to the transport
equation $\partial_t \mu = \text{div}(\mu \nabla V)$)

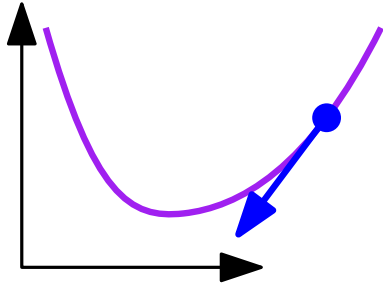


1 - Derivation of the limit flow as $\tau \rightarrow 0$

2 - Interlude: the Riemannian geometry of Sinkhorn divergences

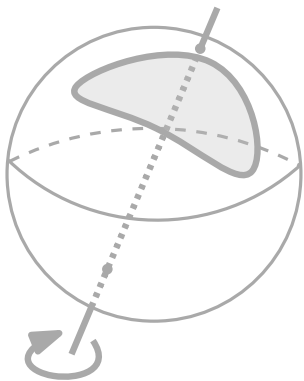
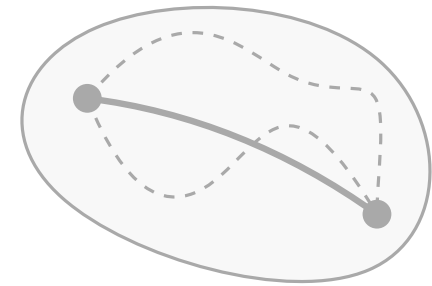


3 - Existence, stability and long term behavior of the flow



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Technical preliminaries: Schrödinger potentials

$(f_{\mu,\nu}, g_{\mu,\nu})$ **Schrödinger potentials**, solutions of:
$$\begin{cases} f = T_\varepsilon(g, \nu), \\ g = T_\varepsilon(f, \mu), \end{cases}$$

with $T_\varepsilon(f, \mu) = -\varepsilon \log \int_X \exp \left(\frac{f(x) - c(x, \cdot)}{\varepsilon} \right) d\mu(x).$

Proposition

$$\frac{\delta \text{OT}_\varepsilon(\mu, \nu)}{\delta(\mu, \nu)} = (f_{\mu,\nu}, g_{\mu,\nu}).$$

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Definition:

$$k_{\mu,\nu}(x, y) = \exp \left(\frac{f_{\mu,\nu}(x) + g_{\mu,\nu}(y) - c(x, y)}{\varepsilon} \right).$$

π_ε entropic optimal plan between μ and ν is:

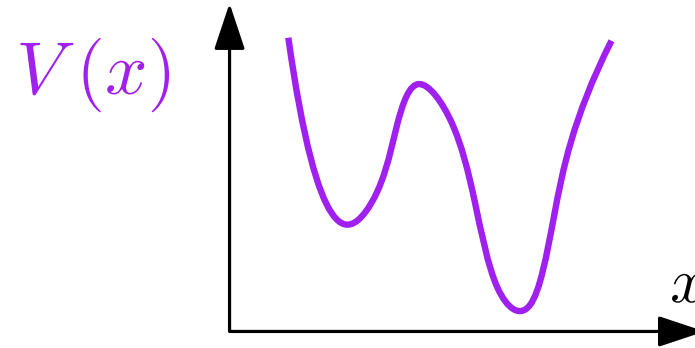
$$\pi_\varepsilon = k_{\mu,\nu} \cdot (\mu \otimes \nu).$$

Optimality conditions of SJKO

Sinkhorn JKO:

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Lemma. For any k , there exists $p_k^\tau \leq 0$ with $p_k^\tau = 0$ on $\text{supp}(\mu_{k+1}^\tau)$ s.t.

$$\frac{f_{\mu_{k+1}^\tau, \mu_k^\tau} - f_{\mu_{k+1}^\tau, \mu_{k+1}^\tau}}{2\tau} + V + p_k^\tau = \text{Cst.}$$

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Must be related to $\mu_{k+1}^\tau - \mu_k^\tau$

Equation of the limit flow

Define

$$K_\mu[\phi](x) = \int_X k_{\mu,\mu}(x, y) \phi(y) \, d\mu(y),$$

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Theorem (informal)

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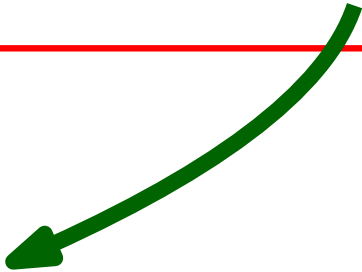
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Recall: SJKO yields


$$\frac{f_{\mu_{k+1}^\tau, \mu_k^\tau} - f_{\mu_{k+1}^\tau, \mu_{k+1}^\tau}}{2\tau} + V + p_k^\tau = \text{Cst.}$$

[Carlier & Laborde, 2020], [Sanz, Loubes, and Niles-Weed, 2022],
[Lavenant, Luckhardt, Mordant, Schmitzer, Tamanini, 2024]

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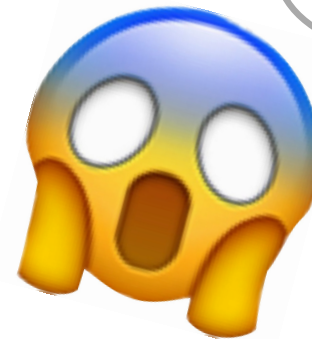
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So $\dot{\mu}_t = H_{\mu_t}^{-1}[\dots]$ with H_{μ_t} “convolution”.
Non local equation of infinite order.



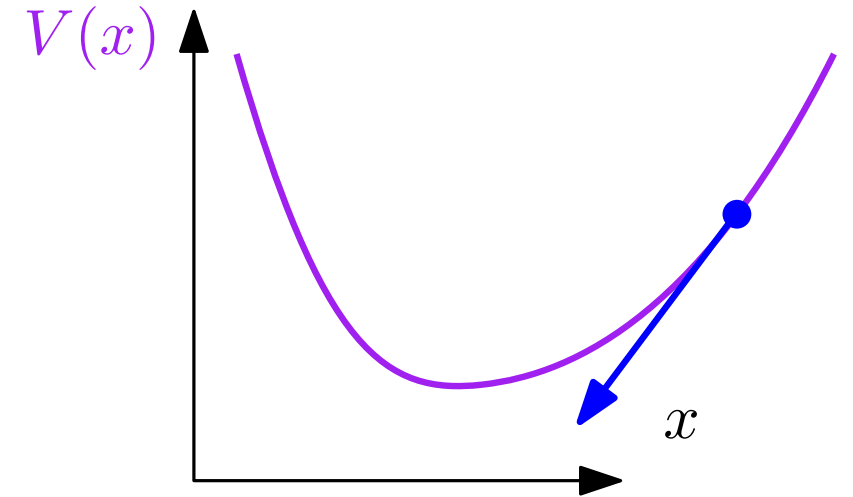
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Examples

Proposition. If $X = \mathbb{R}^d$, V convex, c quadratic cost and $\mu_0 = \delta_{x_0}$ then $\mu_t = \delta_{x_t}$ with

$$\dot{x}_t \in -\partial V(x_t).$$

(Same as Wasserstein GF).

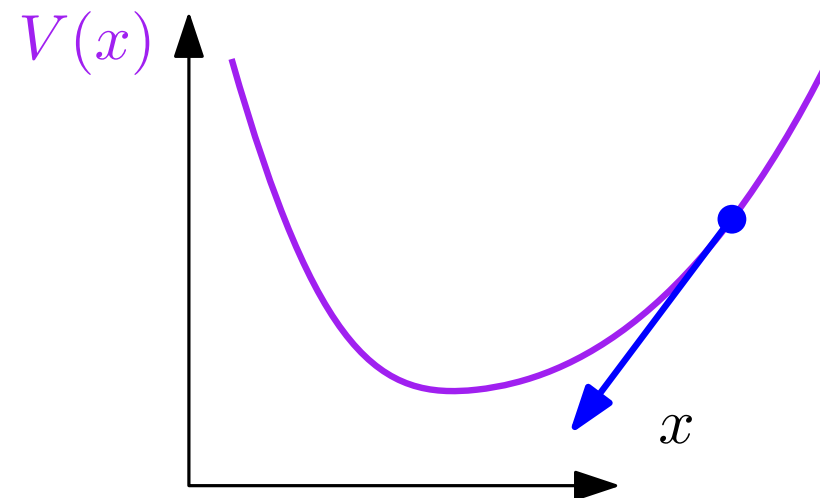


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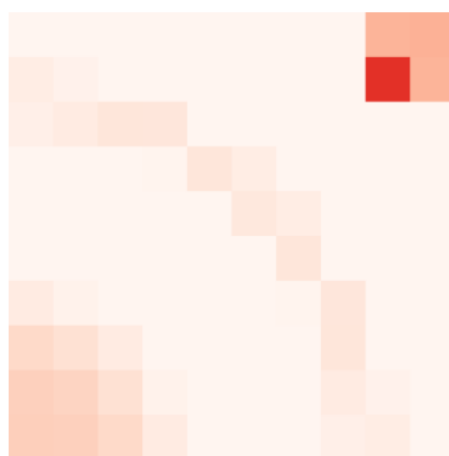


But if V not convex there can be **teleportation**!

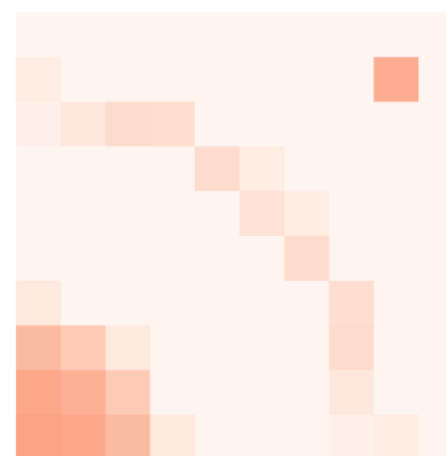
Here a **Lagrangian** discretization won't work.



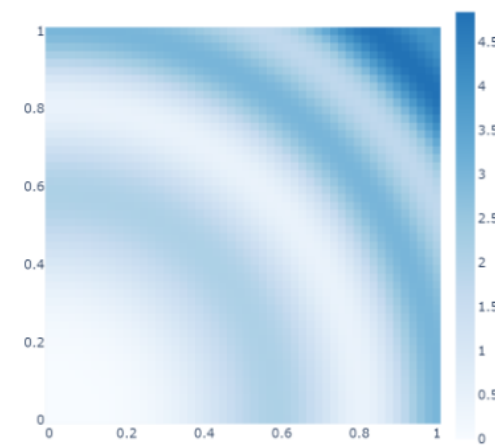
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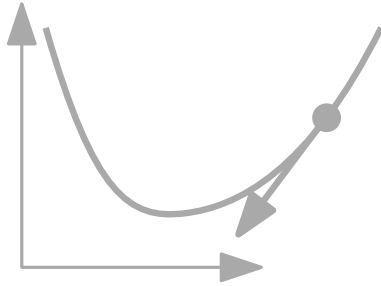
$t = 0.25$



$t = 0.50$

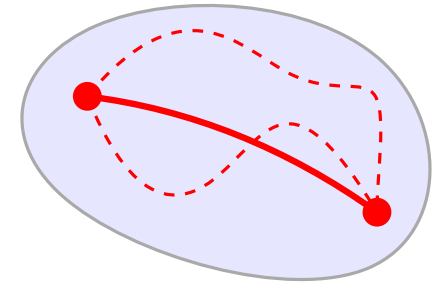


V



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Joint work with:



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G. Mordant



B. Schmitzer



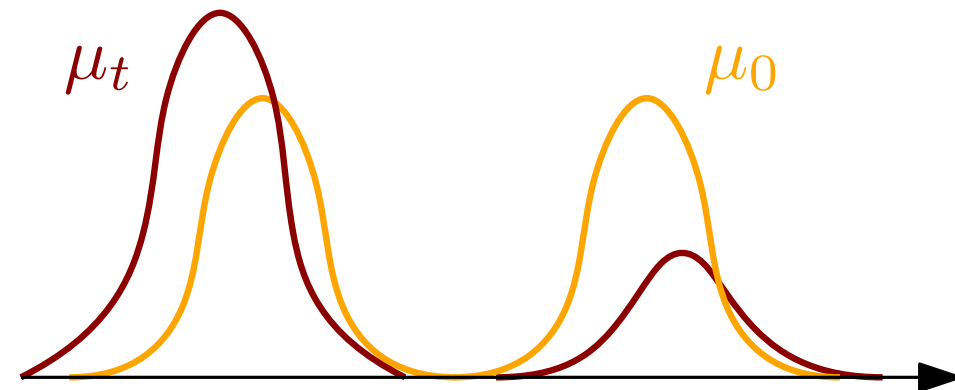
L. Tamanini

The Hessian of the Sinkhorn divergence

$(\mu_t)_t$ curve with $\dot{\mu}_t \in C^m(X)^*$ and $c \in C^{2m}(X \times X)$.

Theorem.

$$S_\varepsilon(\mu_0, \mu_t) \sim t^2 \frac{\varepsilon}{2} \langle \dot{\mu}, (\text{Id} - K_\mu^2)^{-1} H_\mu[\dot{\mu}] \rangle.$$



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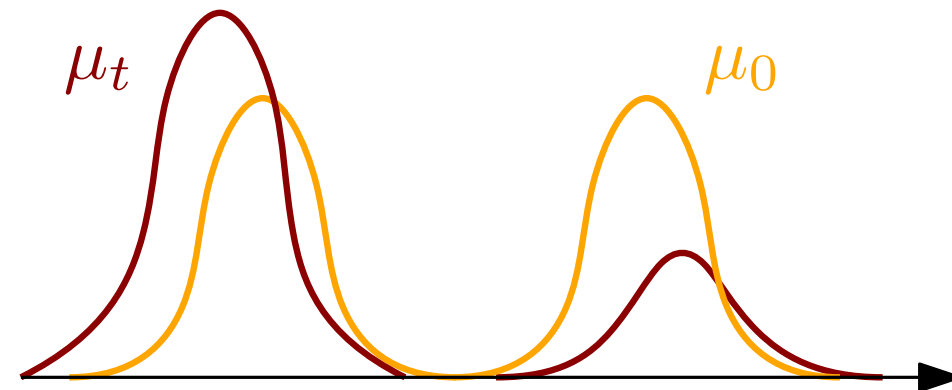
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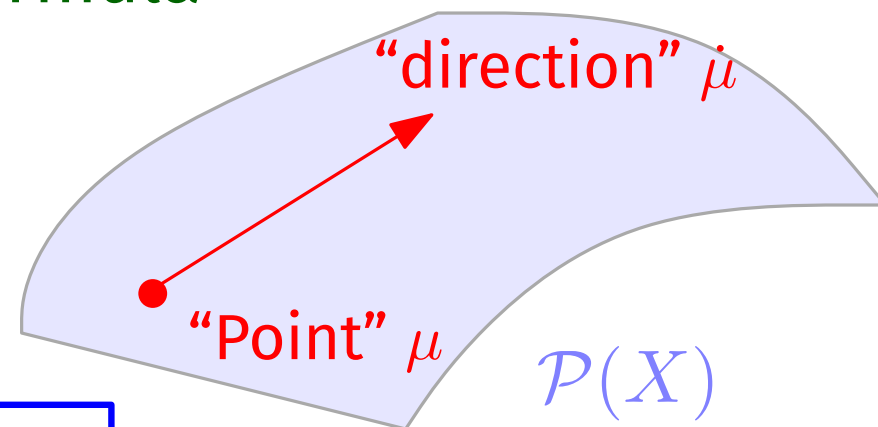


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Same formula



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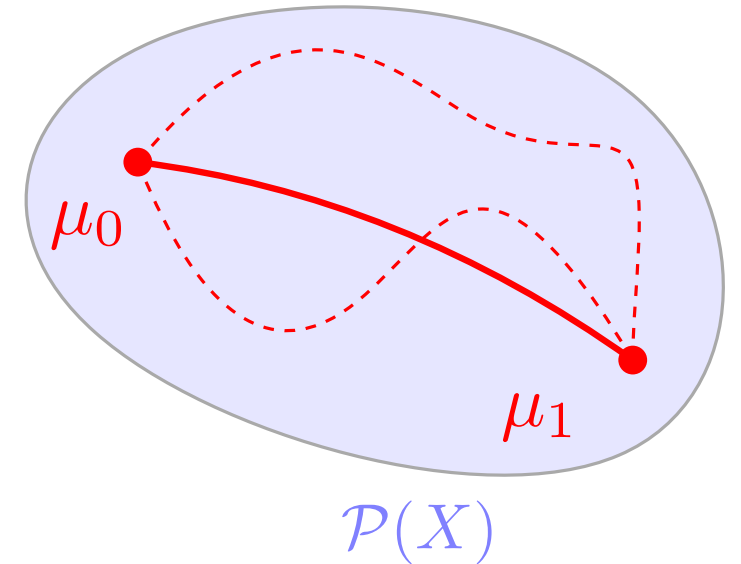
Definition of the Riemannian distance

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Definition. Given μ_0, μ_1 :

$$\mathbf{d}_S(\mu_0, \mu_1)^2 = \inf \int_0^1 \mathbf{g}_{\mu_t}(\dot{\mu}_t, \dot{\mu}_t) dt$$

where infimum over $(\mu_t)_t$ in a suitable class of paths.



Both “vertical” and “horizontal” motion is allowed!

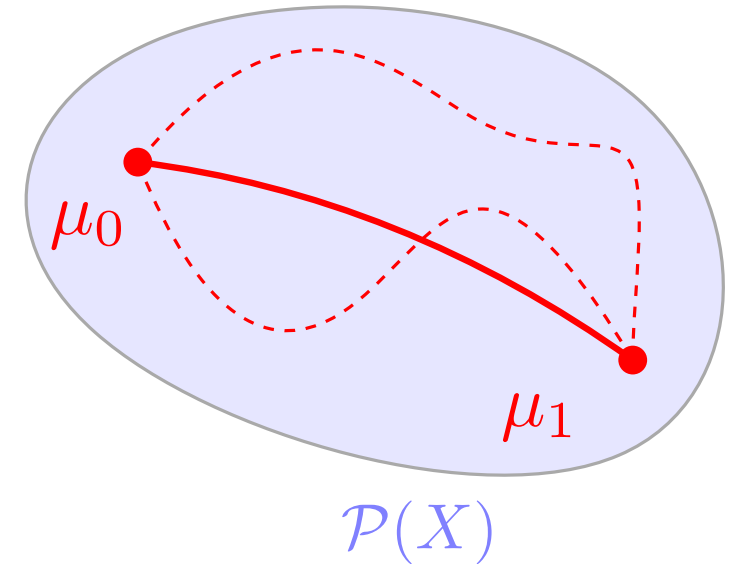
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Theorem. d_S is a distance over $\mathcal{P}(X)$ **metrizing weak convergence of measures**, and the infimum in the definition is reached (**geodesics exist**).

Link with the Sinkhorn potential flow

Sinkhorn potential flow

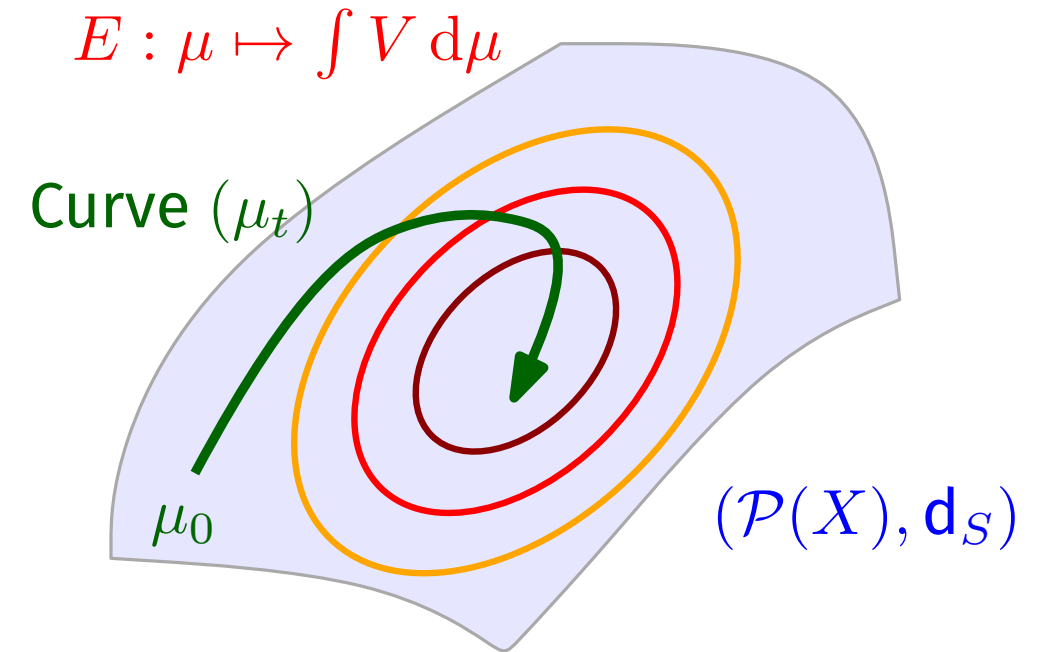
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Metric tensor

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Distance

$$\mathbf{d}_S(\mu_0, \mu_1)^2 = \inf \int_0^1 \mathbf{g}_{\mu_t}(\dot{\mu}_t, \dot{\mu}_t) dt.$$



Link with the Sinkhorn potential flow

Sinkhorn potential flow

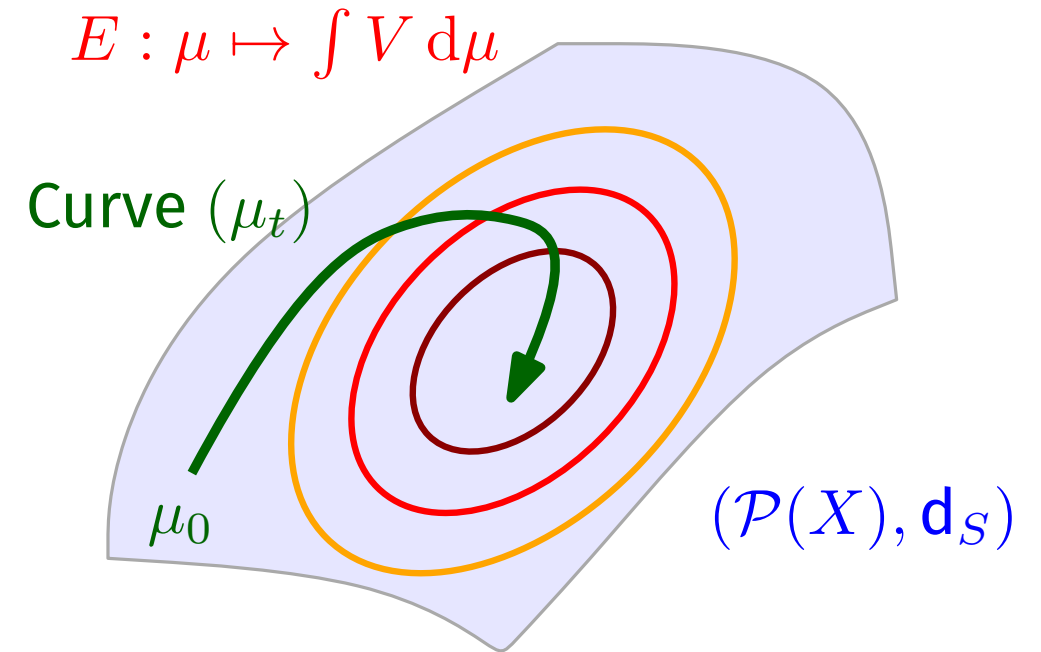
$$\frac{\varepsilon}{2}(\text{Id} - K_{\mu_t}^2)^{-1} H_{\mu_t}[\dot{\mu}_t] + V + p_t = \text{Cst.}$$

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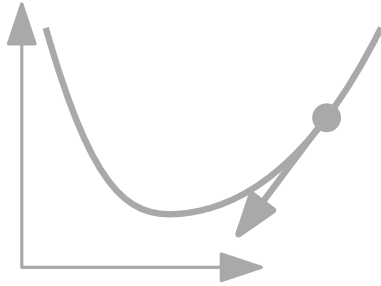
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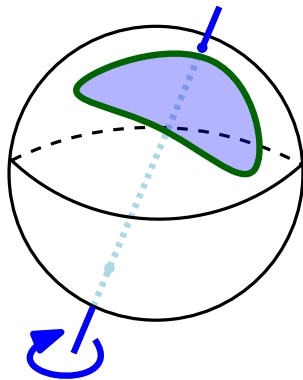
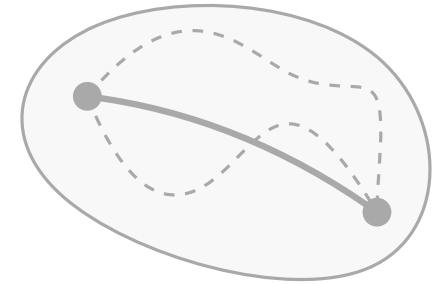
Claim: the Sinkhorn potential flow is formally the **gradient flow** of E in the Riemannian manifold $(\mathcal{P}(X), \mathbf{g})$.

e.g. $\mathbf{g}_{\mu_t}(\dot{\mu}_t, z) + DE(\mu_t)(z) \geq 0$ for all $z \in T_{\mu_t} \mathcal{P}(X)$ admissible tangent vector.



1 - Derivation of the limit flow as $\tau \rightarrow 0$

2 - Interlude: the Riemannian geometry of Sinkhorn divergences



3 - Existence, stability and long term behavior of the flow

Main theoretical results

Sinkhorn potential flow: $\frac{\varepsilon}{2}(\text{Id} - K_{\mu_t}^2)^{-1} H_{\mu_t}[\dot{\mu}_t] + V + p_t = \text{Cst.}$

Theorem. (X compact, $\exp(-c/\varepsilon)$ p.d. universal, V continuous)

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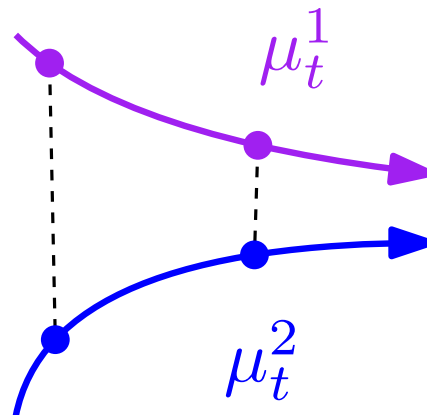
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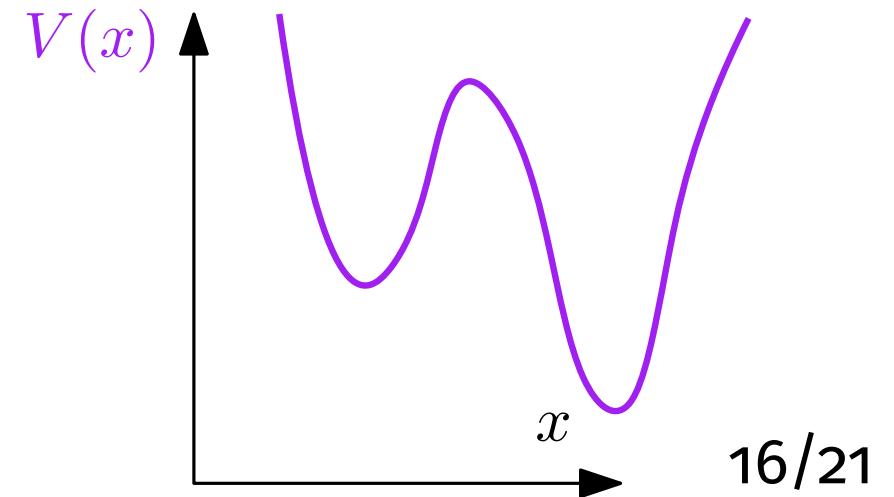
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1. **Existence:** for any μ_0 , there exists a global solution $(\mu_t)_{t \geq 0}$.
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3. Convergence to **global minimum**: $E(\mu_t) \rightarrow \min E$ as $t \rightarrow +\infty$.

Recall. The flow of the Wasserstein GF $\partial \mu_t = \text{div}(\mu_t \nabla V)$ gets trapped in local minima.



The key change of variables into a Reproducing Kernel Hilbert Space

Recall $k_c = \exp(-c/\varepsilon) : X \times X \rightarrow \mathbb{R}$ positive definite and universal.

Definition. $\mathcal{H}_c$ Hilbert space of functions $X \rightarrow \mathbb{R}$: completion of
 $\text{span} \{k_c(\cdot, x) : x \in X\}$
with $\langle k_c(\cdot, x), k_c(\cdot, y) \rangle_{\mathcal{H}_c} = k_c(x, y)$.

k_c positive definite if this
defines dot product



$(k_c \text{ universal} \Leftrightarrow \mathcal{H}_k \text{ dense in } C(X))$

[Paulsen & Raghupathi, 2016]

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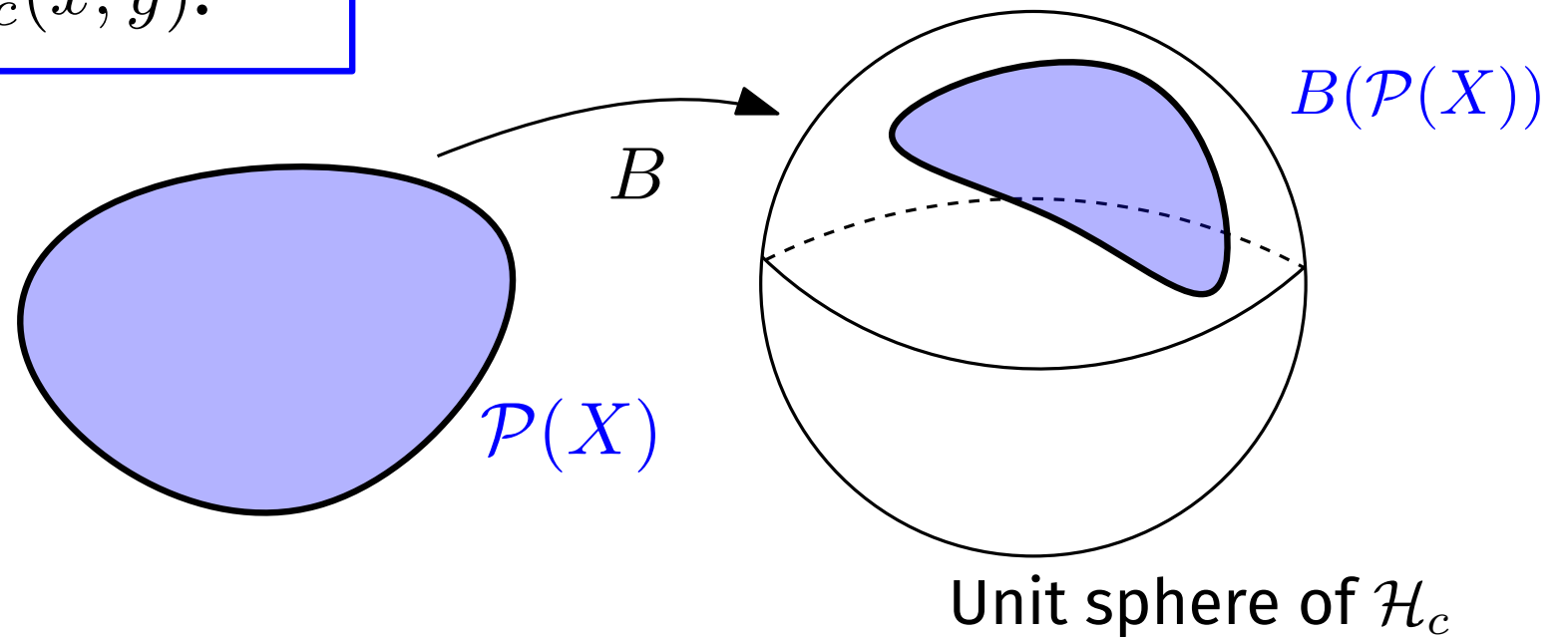
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Theorem. The map B is an homeomorphism between $\mathcal{P}(X)$ and the intersection of a convex cone and the unit sphere of $\mathcal{H}_c$.



Sinkhorn flow in the Hilbert space $\mathcal{H}_c$

With $b_t = \exp(-f_{\mu_t, \mu_t}/\varepsilon) \in \mathcal{H}_c$ and $V : X \rightarrow \mathbb{R}$.

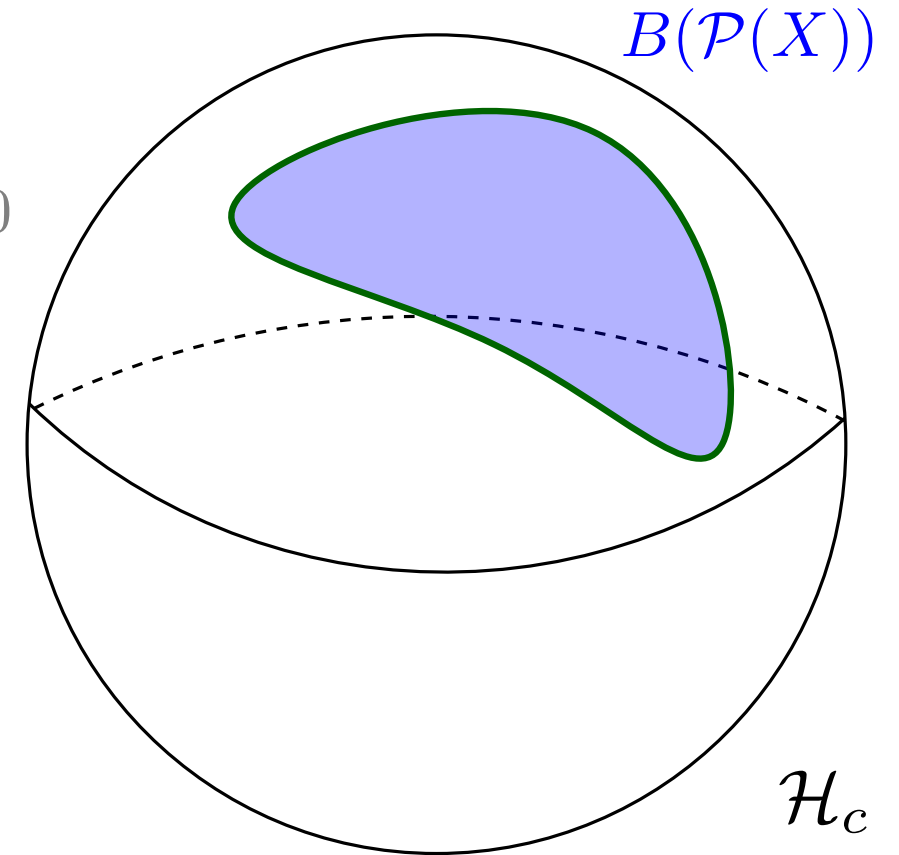
Sinkhorn flow in the b -variable.

$$\dot{b}_t + \frac{2}{\varepsilon} (V - V^*) b_t + p_t = 0.$$

multiplication by V
in $\mathcal{H}_c$

V^* Adjoint of multiplication
by V for $\langle \cdot, \cdot \rangle_{\mathcal{H}_c}$

$p_t \leq 0$, and $p_t = 0$
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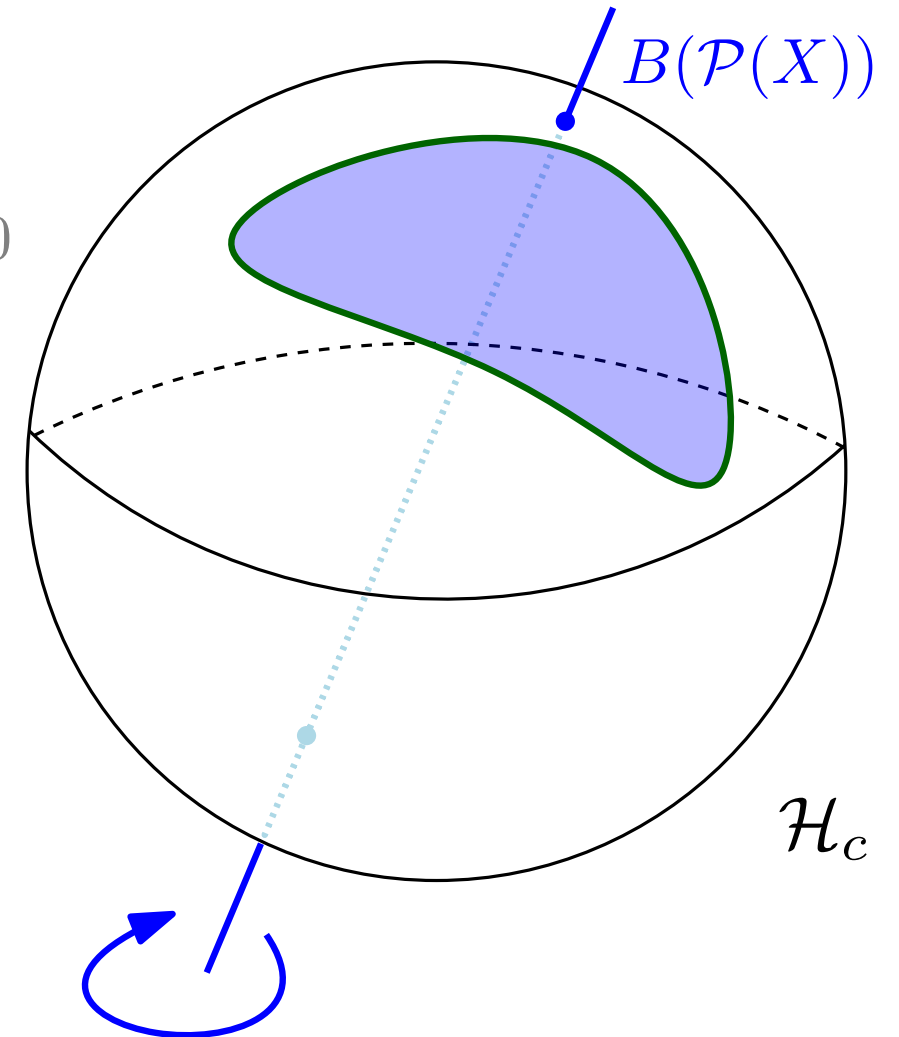
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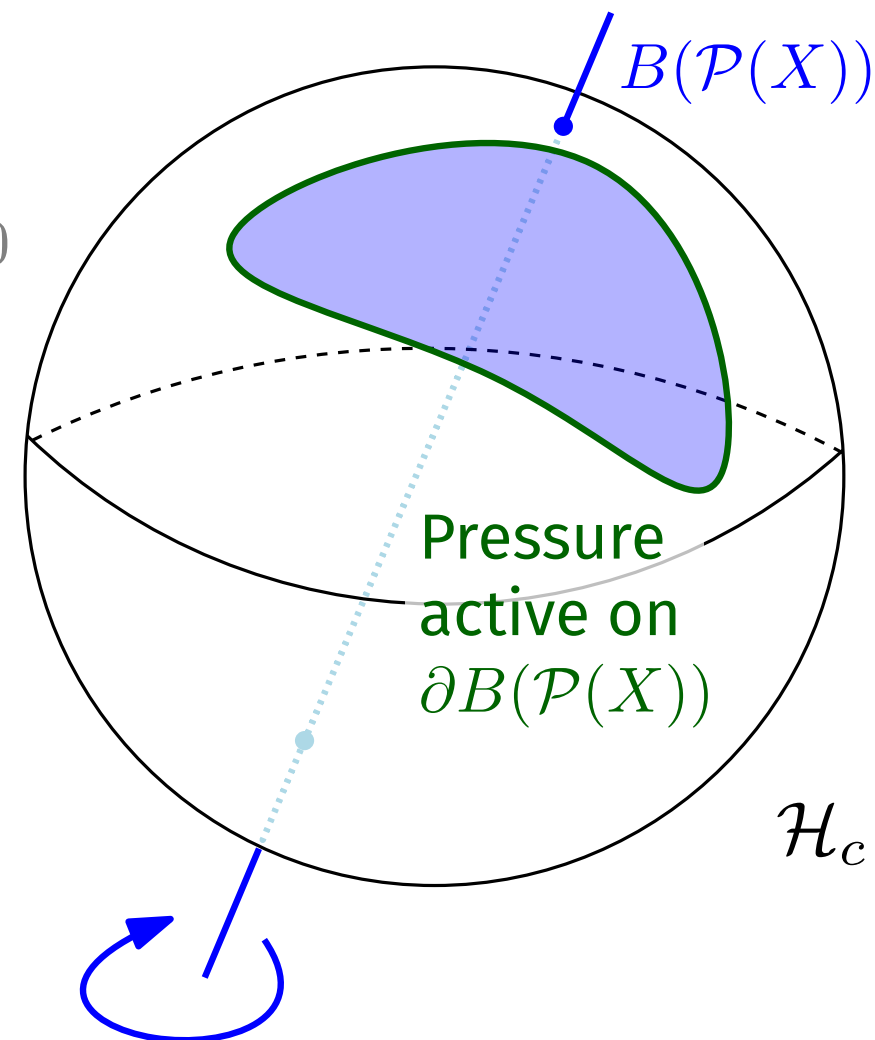
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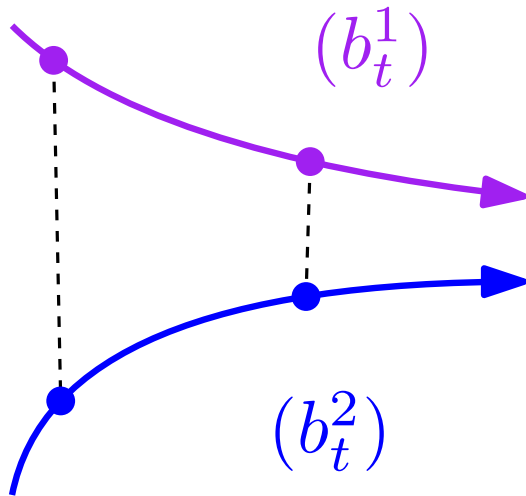
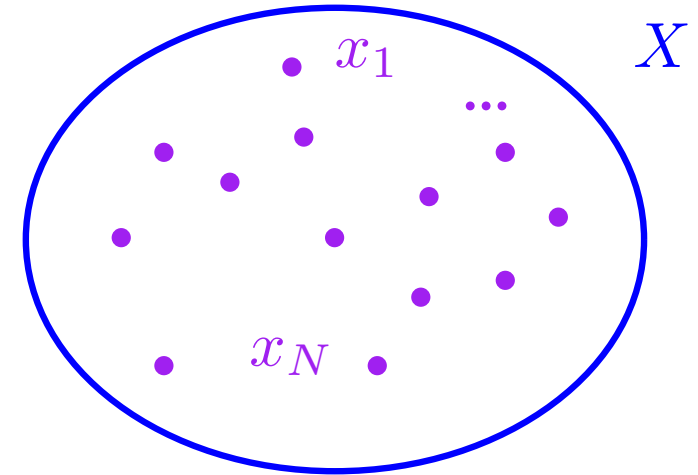
Pressure: in the polar cone of
 $B(\mathcal{M}_+(X))$ for $\langle \cdot, \cdot \rangle_{\mathcal{H}_c}$, maintains $\mu_t \geq 0$.



“Rotation” generated by $\frac{2}{\varepsilon}(V - V^*)$

Proof ideas of the main results

Proof idea for existence: approximate X by a finite space $X_N = \{x_1, \dots, x_N\}$. For measures supported on X_N , the Sinkhorn flow is a maximal monotone evolution.



Proof idea of non-expansiveness: Monotone evolutions are non-expansive thus $\|b_t^1 - b_t^2\|_{\mathcal{H}_c}$ decreases.

Link with the Sinkhorn JKO scheme

Sinkhorn JKO:

$$\mu_{k+1}^\tau \in \arg \min_{\mu} E(\mu) + \frac{S_\varepsilon(\mu, \mu_k^\tau)}{2\tau}.$$

with S_ε Sinkhorn divergence and $E(\mu) = \int V \, d\mu$ **potential energy**.

Sinkhorn potential flow

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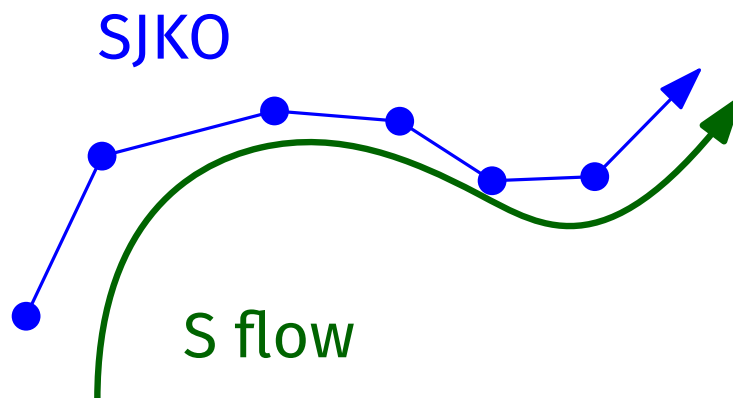
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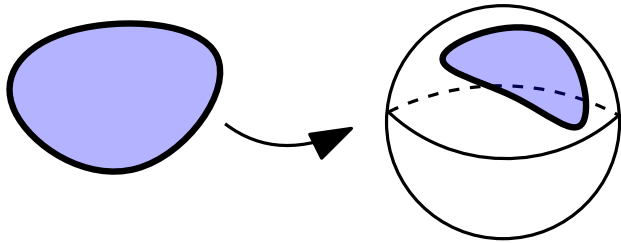
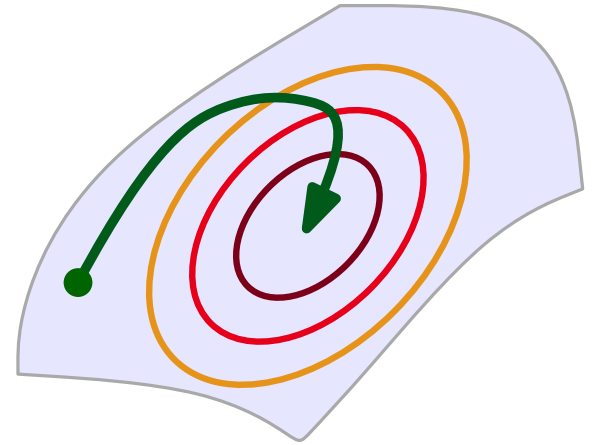


Proposition. If X is a **finite set**, the solutions of the Sinkhorn JKO scheme, properly interpolated in time, converge to the Sinkhorn flow as $\tau \rightarrow 0$ in $C([0, T], \mathcal{P}(X))$.

Future works

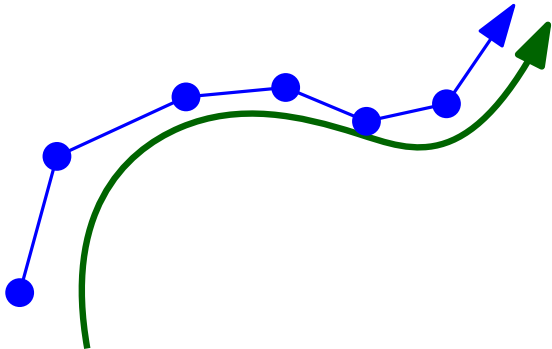
What I have not presented:

- our results on the geometry of Sinkhorn divergences.



Some topics worth exploring:

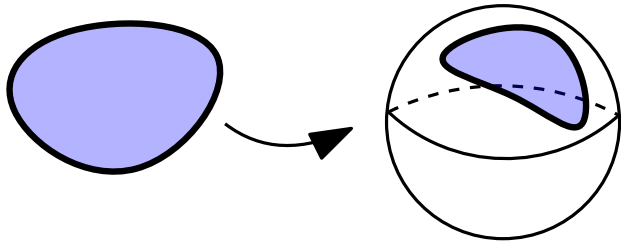
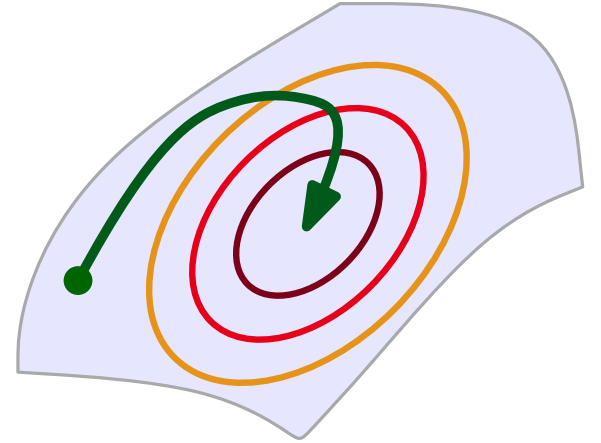
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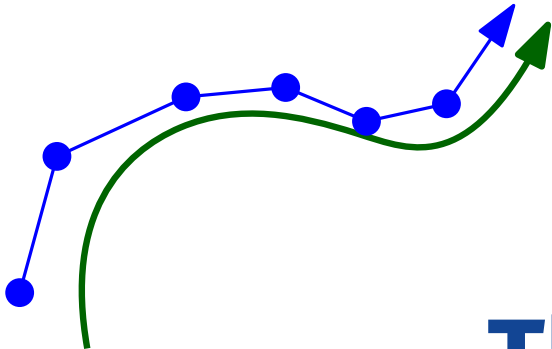
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Thank you for your attention